Patent Claims

- A computer for analyzing data from nuclear magnetic resonance, whereby the 1. data contains at least one relaxation signal of a sample, characterized in that the computer operates with at least one analyzing means that separates the data into at least two parts that are differently dependent on an echo time TE.
- The computer according to Claim 1, characterized in that the analyzing means 2. separates the data into at least one part that is dependent on an echo time TB and into at least one more component that is not dependent on the echo time TE and whereby the analyzing means acquires the signals that are dependent on an echo time T_B as activation signals.

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- A nuclear magnetic resonance tomograph characterized in that it comprises at 3. least one computer according to one of Claims 1 or 2.
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 - A method to analyze data from nuclear magnetic resonance, whereby at least one relaxation signal of a sample is detected, characterized in that the data is separated into at least two parts having a different dependence on an echo time Te.
 - The method according to Claim 4, characterized in that the intensity values of 5. the measured data are acquired and separated into at least two different dependencies on the echo time T₅.
 - The method according to Claim 5, characterized in that a measure of a statistical 6. variation of the intensities is determined.
 - 7. The method according to Claim 6, characterized in that a standard deviation of the intensities is ascertained.

AA Sub	8.	The method according to one of Claims 4 through 7, characterized in that the
		relaxation signal is divided into at least one part that is dependent on the echo time
		T_E and into at least one part that is not dependent on the echo time T_E .
	9.	The method according to one of Claims 4 through 8, characterized in that at
		least one signal is determined that is proportional to $T_E \exp(-T_E/T_2^*)$.
Suly	10.	The method according to Claim 9, characterized in that T ₂ is ascertained with
(5)		the formula $S = S_0 \exp \left(-\frac{T_E}{T_1}\right) + g$.
Sub	11.	The method according to one or more of Claims 4 through 10, characterized in
A3.D		that statistical fluctuations of ΔT_2 are ascertained.
5.15	12.	The method according to Claim 11, characterized in that a standard deviation
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	13.	The method according to Claim 12, characterized in that a quotient $\sigma(\Delta T_2^*)$
! 년 :		/ T ₂ is formed and acquired as a measure of an activity.
		and account to a measure of all activity.
SUB	14.	The method according to one of Claims 4 through 13, characterized in that a sta-
		tistical deviation of an initial intensity So is ascertained.
6.12	15.	The method according to Claim 14, characterized in that a standard deviation
Sul		σ (ΔS_0) is ascertained.
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₹	16.	The method according to Claim 15, characterized in that a quotient $\sigma(\Delta S_0)$ /
_ <u> </u>		ΔS_0 is ascertained.

17. The method according to one of Claims 4 through 16, characterized in that a statistical fluctuation of a noise signal g is ascertained.

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18. The method according to Claim 17, characterized in that a standard deviation σ (g) of g is formed.

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19. The method according to one of Claims 4 through 18, characterized in that the recorded data is acquired in an at least two-dimensional field, whereby a field axis (DTE) acquires echo times T_B and whereby another field axis (DTR) reproduces repetitions of excitations at a time interval T_R.

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- 20. The method according to Claim 19, characterized in that $\sigma(\Delta T_2)$ and $\sigma(g)$ are determined by means of the following steps:
 - (i) adaptation of signals averaged over DTR to an exponential decay as a function of DTE and determination of S₀ and T;
 - (ii) calculation of $\sigma(\Delta S_0)$, $\sigma(\Delta T_2^*)$ and $\sigma(g)$ for several voxels and different T_E , followed by averaging of these values over at least one region of interest (ROI);
 - (iii) adaptation of

$$\frac{\sigma(\Delta S)}{S_{0}} = \left\{ \left[\left(\frac{T_{E}}{T_{2}^{*}} \right)^{2} \left(\frac{\sigma(\Delta T_{2}^{*})}{T_{2}^{*}} \right)^{2} + \left(\frac{\sigma(\Delta S_{0})}{S_{0}} \right)^{2} - 2 \frac{T_{E}}{T_{2}^{*}} \frac{\left\langle \Delta S_{0} \Delta T_{2}^{*} \right\rangle}{S_{0} T_{2}^{*}} \right] \varepsilon^{-2 T_{E} / T_{2}^{*}} + \left(\frac{\sigma(g)}{S_{0}} \right)^{2} \right\}^{1/2}$$

and determination of $\sigma(\Delta S) / S_0$ as a function of T_R .

21. The method according to Claim 20, characterized in that the expression $\langle \Delta S_0 \Delta T_0^* \rangle = 0$ is used for the adaptation of $\sigma (\Delta S_0) / S_0$.